

# Solving Life-Cycle Models with a Rich Asset Structure using Deep Learning

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based on joint work with Jan Žemlička,<sup>2,3</sup> Luca Gaegauf,<sup>2</sup> and Simon Scheidegger<sup>4,5</sup>

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# Motivation

- ▶ Economic models to study questions related to **aggregate risk** and **asset pricing**, often require **global solution methods** to compute equilibria
- ▶ Computing a functional rational expectations equilibrium amounts to computing a **set of functions**,  $f_i$ , mapping the **state of the economy**,  $\mathbf{x}$ , to **endogenous outcomes**  $f_i(\mathbf{x})$ :

$$f_i : \mathcal{D} \subset \mathbb{R}^{N_{\text{in}}} \rightarrow \mathbb{R} : \underbrace{\mathbf{x}}_{\text{state}} \rightarrow \underbrace{f_i(\mathbf{x})}_{\text{endogenous variables}}, \text{ s.t. : } \underbrace{\mathbf{G}(\mathbf{x}, f_1, \dots, f_{N_{\text{out}}}) = 0}_{\text{equilibrium conditions}}$$

- ▶ This can be a computationally demanding task, especially when
  - ▶ the **state** of the economy is **high-dimensional**
  - ▶ the equilibrium **functions** are **nonlinear**
- ▶ Both often happens for **Overlapping Generations (OLG)** models:
  - ▶ the state includes the wealth distribution across age-groups
  - ▶ young households are often constrained
  - ▶ may want to account for portfolio decomposition and volatility of labor income, both of which have strong lifecycle components

# This talk

- ▶ Basic solution method developed in Azinovic et al. (2022)
- ▶ More recent progress on portfolio choice and market clearing neural network architectures developed in Azinovic and Žemlička (2023)

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- ▶ More recent progress on portfolio choice and market clearing neural network architectures developed in Azinovic and Žemlička (2023)
- ▶ Other papers on deep learning based solution methods I learned a lot from: Maliar et al. (2021); Kase et al. (2023); Gu et al. (2023); Kahou et al. (2021); Han et al. (2022); Valaitis and Villa (2024); Kahou et al. (2022); Fernández-Villaverde et al. (2023); Barnett et al. (2023); Jungerman (2023); Kahou et al. (2024)

# Deep Equilibrium Nets

# Violations of equilibrium conditions as loss function

Basic idea in Azinovic et al. (2022): write equilibrium conditions as

$$\mathbf{G}(\mathbf{x}, \mathbf{f}) = 0 \quad \forall \mathbf{x}$$

$\mathbf{G}$  : equilibrium conditions: FOC's, market clearing, Bellman equations, ...

$\mathbf{x}$  : state of the economy

$\mathbf{f}$  : equilibrium functions.

Approximate  $\mathbf{f}$  by neural network  $\mathcal{N}_\rho$

$$\mathcal{N}_\rho(\mathbf{x}) \approx \mathbf{f}(\mathbf{x})$$

How?

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How?

Standard deep learning:

- ▶ need labeled data, i.e. inputs for which we know the true output:  $\{\mathbf{x}_i, f(\mathbf{x}_i)\}_i$
- ▶ train neural network parameters  $\rho$  to minimize the **loss function**

$$\ell_\rho := \frac{1}{N_{\text{labeled data}}} \sum_{\mathbf{x}_i} (f(\mathbf{x}_i) - \mathcal{N}_\rho(\mathbf{x}_i))^2$$

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Deep equilibrium nets:

- ▶ use equilibrium conditions directly as **loss function**

$$\ell_\rho := \frac{1}{N_{\text{path length}}} \sum_{\mathbf{x}_i \text{ on sim. path}} (\mathbf{G}(\mathbf{x}_i, \mathcal{N}_\rho))^2$$

- ▶ no need for labeled data!

▶ What are Neural Nets?

▶ Why use Neural Nets?



# Training DEQNs

1. Simulate a sequence of states  $\mathcal{D}_{\text{train}}^i \leftarrow \{\mathbf{x}_1^i, \mathbf{x}_2^i, \dots, \mathbf{x}_T^i\}$  from the policy encoded by the network parameters  $\rho^i$ .
2. Evaluate the errors of the equilibrium conditions on the newly generated set  $\mathcal{D}_{\text{train}}$ .
3. If the error statistics are not low enough:
  - 3.1 update the parameters of the neural network with a gradient descent step (or a variant):

$$\rho_k^{i+1} = \rho_k^i - \alpha_{\text{learn}} \frac{\partial \ell_{\mathcal{D}_{\text{train}}^i}(\rho^i)}{\partial \rho_k^i}.$$

- 3.2 set new starting states for simulation:  $\mathbf{x}_0^{i+1} = \mathbf{x}_T^i$ .
  - 3.3 increase  $i$  by one and go back to step 1.

# Illustrative Model

# Illustrative OLG model with capital and bond

- ▶ Representative firm produces with

$$\begin{aligned}F(z_t, K_t, L) &= z_t K_t^\alpha L^{1-\alpha} \\ w_t &= \alpha z_t K_t^{\alpha-1} L^{1-\alpha} \\ r_t &= z_t (1-\alpha) K_t^\alpha L^{-\alpha}\end{aligned}$$

- ▶ Uncertainty in TFP  $z_t$ , and depreciation of capital  $\delta_t$

$$\begin{aligned}\log(z_{t+1}) &= \rho_z \log(z_t) + \sigma_z \epsilon_t \\ \epsilon_t &\sim N(0, 1) \\ \delta_t &= \delta \frac{2}{1+z}\end{aligned}$$

- ▶ Assets

- ▶ one period bond with price  $p_t$  in aggregate supply  $B$
- ▶ risky capital  $K_t$
- ▶ borrowing constraints on both assets

$$\begin{aligned}b_t^h &\geq 0 \\ k_t^h &\geq 0\end{aligned}$$

- ▶ Households

- ▶  $H = 32$  age-groups, indexed with  $h \in \mathcal{H} := \{1, \dots, 32\}$
- ▶ supply labor units  $l_t^h$  inelastically
- ▶ adjustment costs on capital

$$\begin{aligned}\Delta_{k,t}^h &:= k_{t+1}^h - k_t^h \\ \text{adj. costs} &= \psi \left( \Delta_{k,t}^h \right)^2\end{aligned}$$

- ▶ budget constraint

$$\begin{aligned}c_t^h &= l^h w_t + b_{t-1}^{h-1} + k_{t-1}^{h-1} (1 - \delta_t + r_t) \\ &\quad - p_t^b b_t^h - k_t^h - \psi \left( \Delta_{k,t}^h \right)^2\end{aligned}$$

- ▶ maximize

$$\begin{aligned}E \left[ \sum_{i=h}^H \beta^{i-h} u(c_{t+i}^h) \right] \\ u(c) := \frac{c^{1-\gamma} - 1}{1-\gamma}\end{aligned}$$

# Equilibrium conditions

► **Market clearing:**

$$K_t := \sum_{h \in \mathcal{H}} k_t^h$$
$$B = \sum_{h \in \mathcal{H}} b_t^h \Leftrightarrow \epsilon_t^B := B - \sum_{h \in \mathcal{H}} b_t^h = 0$$

► **Firms optimize:**

$$w_t := \alpha z_t K_t^{\alpha-1} L^{1-\alpha}$$
$$r_t := z_t (1 - \alpha) K_t^\alpha L^\alpha$$

► **Households optimize:**

- $H$  sets of Karush Kuhn Tucker conditions for bond  
⇒ single equation using the Fisher-Burmeister equation  
⇒  $H$  errors  $\epsilon_t^{k,i}$
- $H$  sets of Karush Kuhn Tucker conditions for capital  
⇒ single equation using the Fisher-Burmeister equation  
⇒  $H$  errors  $\epsilon_t^{h,i}$

# Approximation with standard DEQN

- ▶ State of the economy

$$\mathbf{x}_t = [ \underbrace{z_t}_{\text{ex. shock}}, \underbrace{k_t^1, \dots, k_t^{32}}_{\text{dist. of cap.}}, \underbrace{b_t^1, \dots, b_t^{32}}_{\text{dist. of bonds}} ]$$

- ▶ Equilibrium policies

$$\mathbf{f}(\mathbf{x}_t) = [ \underbrace{k_{t+1}^1, \dots, k_{t+1}^{32}}_{\text{capital policy}}, \underbrace{b_{t+1}^1, \dots, b_{t+1}^{32}}_{\text{bond policy}}, \underbrace{p_t^b}_{\text{bond price}} ]$$

- ▶ Neural network approximates

$$\mathcal{N}_\rho(\mathbf{x}_t) = [ \underbrace{\hat{k}_{t+1}^1, \dots, \hat{k}_{t+1}^{32}}_{\text{capital policy}}, \underbrace{\hat{b}_{t+1}^1, \dots, \hat{b}_{t+1}^{32}}_{\text{bond policy}}, \underbrace{\hat{p}_t^b}_{\text{bond price}} ] \approx \mathbf{f}(\mathbf{x}_t)$$

- ▶ Loss function

$$\ell_\rho(\mathbf{x}_t) := \underbrace{w_{hh,k}}_{\text{weight}} \underbrace{\left( \sum_{h=1}^{H-1} (\epsilon_t^{k,h})^2 \right)}_{\text{opt. cond. cap.}} + \underbrace{w_{hh,b}}_{\text{weight}} \underbrace{\left( \sum_{h=1}^{H-1} (\epsilon_t^{b,h})^2 \right)}_{\text{opt. cond. bond}} + \underbrace{w_{mc,B}}_{\text{weight}} \underbrace{(\epsilon_t^B)^2}_{\text{market clearing}}$$

# Innovation 1: Market clearing layers

- ▶ Neural network first predicts

$$\mathcal{N}_\rho^{\text{pre}}(\mathbf{x}_t) = [\hat{k}_{t+1}^1, \dots, \hat{k}_{t+1}^{32}, \tilde{b}_{t+1}^1, \dots, \tilde{b}_{t+1}^{32}, \hat{p}_t^b]$$

- ▶ Apply transformation  $m(\dots, \cdot)$

$$[\hat{b}_{t+1}^1, \dots, \hat{b}_{t+1}^{32}] = m(\mathcal{N}_\rho^{\text{pre}}(\mathbf{x}_t), B)$$

- ▶ Such that

$$B = \sum_{h=1}^{32} \hat{b}_{t+1}^h$$

- ▶ Put together

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1. **no need to learn** economics we already know ex-ante
2. remaining loss **easier to interpret**
3. states simulated from the policy are **always consistent with market clearing**

▶ details

# Innovation 2: Stabilizing step-wise model transformations

- ▶ Single asset models are easy



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- ▶ Why?
  - ▶ portfolio choice only pinned down at low errors in equilibrium conditions
  - ▶ but how do we get there?

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$$\mathcal{N}_\rho^1(\mathbf{x}_t) = [\hat{k}_{t+1}^1, \dots, \hat{k}_{t+1}^{32}, \mathbf{0} \times \hat{b}_{t+1}^1, \dots, \mathbf{0} \times \hat{b}_{t+1}^{32}, \hat{\rho}_t^b], B^1 = \mathbf{0}$$

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3. solve the model

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3. solve the model
4. train the neural network to predict the bond price (supervised, from zero liquidity limit)

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3. solve the model
4. train the neural network to predict the bond price (supervised, from zero liquidity limit)
5. slowly introduce the second asset (such that the error remains low)

$$\mathcal{N}_\rho^2(\mathbf{x}_t) = [\hat{k}_{t+1}^1, \dots, \hat{k}_{t+1}^{32}, \mathbf{1} \times \hat{b}_{t+1}^1, \dots, \mathbf{1} \times \hat{b}_{t+1}^{32}, \hat{p}_t^b], B^2 = 0.1$$

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3. solve the model
4. train the neural network to predict the bond price (**supervised, from zero liquidity limit**)
5. slowly introduce the second asset (**such that the error remains low**)

$$\mathcal{N}_\rho^3(\mathbf{x}_t) = [\hat{k}_{t+1}^1, \dots, \hat{k}_{t+1}^{32}, \mathbf{1} \times \hat{b}_{t+1}^1, \dots, \mathbf{1} \times \hat{b}_{t+1}^{32}, \hat{p}_t^b], B^3 = 0.2$$



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$$\mathcal{N}_\rho^{100}(\mathbf{x}_t) = [\hat{k}_{t+1}^1, \dots, \hat{k}_{t+1}^{32}, \mathbf{1} \times \hat{b}_{t+1}^1, \dots, \mathbf{1} \times \hat{b}_{t+1}^{32}, \hat{p}_t^b], B^{100} = 10$$

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$$\mathcal{N}_\rho^{100}(\mathbf{x}_t) = [\hat{k}_{t+1}^1, \dots, \hat{k}_{t+1}^{32}, \mathbf{1} \times \hat{b}_{t+1}^1, \dots, \mathbf{1} \times \hat{b}_{t+1}^{32}, \hat{p}_t^b], B^{100} = 10$$

6. equilibrium errors **always remain low**

# Application

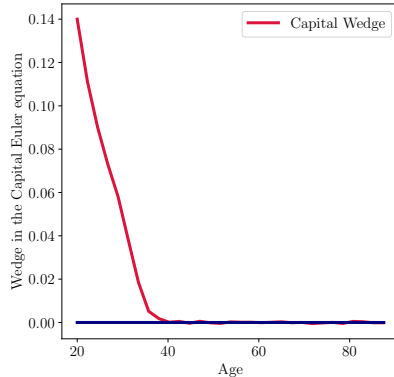
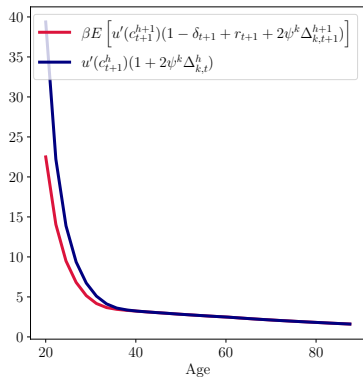
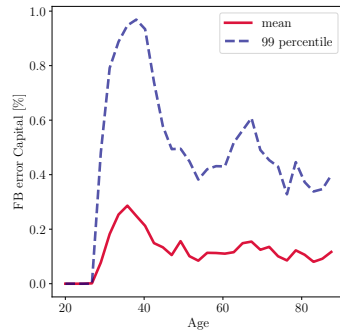
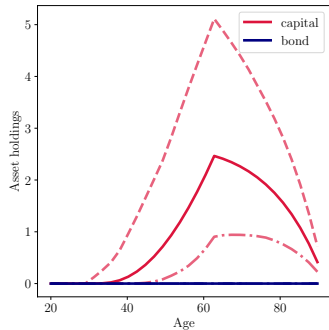
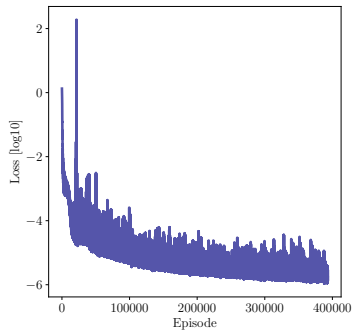
# Step 1: Solve single asset model

- ▶ Borrowing constraint  $\underline{b} = 0$ , net-supply  $B = 0$
- ▶ Neural network predicts

$$\begin{aligned}\mathcal{N}_\rho^{\text{pre}}(\mathbf{x}_t) &= [\hat{k}_{t+1}^1, \dots, \hat{k}_{t+1}^{32}, \mathbf{0} \times \tilde{b}_{t+1}^1, \dots, \mathbf{0} \times \tilde{b}_{t+1}^{32}, \hat{p}_t^b] \\ \Rightarrow \mathcal{N}_\rho(\mathbf{x}_t) &= [\hat{k}_{t+1}^1, \dots, \hat{k}_{t+1}^{32}, \mathbf{0}, \dots, \mathbf{0}, \hat{p}_t^b]\end{aligned}$$

- ▶ Loss function

$$\ell_\rho(\mathbf{x}_t) := \underbrace{\mathbf{1} \times \left( \sum_{h=1}^{H-1} (\epsilon_t^{k,h})^2 \right)}_{\text{opt. cond. cap.}} + \underbrace{\mathbf{0} \times \left( \sum_{h=1}^{H-1} (\epsilon_t^{b,h})^2 \right)}_{\substack{\text{opt. cond. bond} \\ =0}}$$





# Step 2: Pre-train bond price in the capital only model

- ▶ Keep borrowing constraint  $\underline{b} = 0$ , net-supply  $B = 0$ , and neural network masks

$$\mathcal{N}_\rho(\mathbf{x}_t) = [\hat{k}_{t+1}^1, \dots, \hat{k}_{t+1}^{32}, \mathbf{0}, \dots, \mathbf{0}, \hat{p}_t^b]$$

- ▶ In equilibrium we know that

$$p_t^b \geq \frac{\beta \mathbb{E} [u'(c_{t+1}^{h+1})]}{u'(c_t^h)}$$

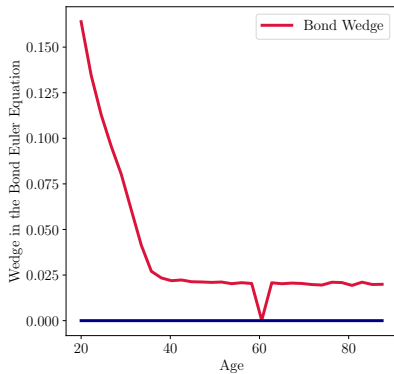
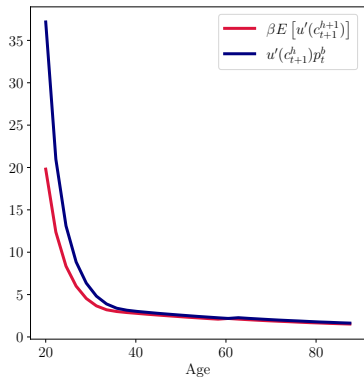
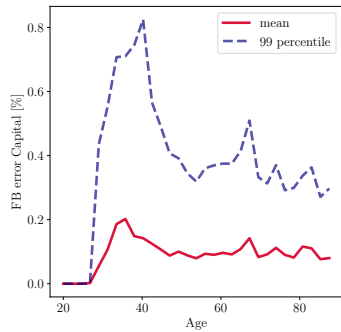
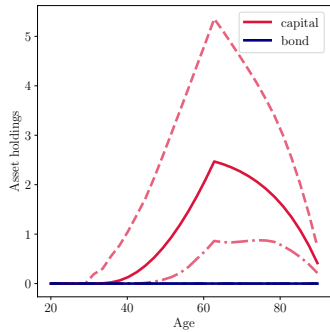
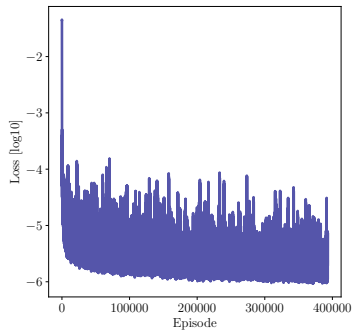
with equality for unconstrained agents.

- ▶ With **market clearing policies**, we have a **closed form expression for the bond price** and can define pre-train price and error

$$p_t^{b, \text{pre-train}} := \max_{h \in \mathcal{H}} \left\{ \frac{\beta \mathbb{E} [u'(c_{t+1}^{h+1})]}{u'(c_t^h)} \right\}$$
$$\epsilon_t^{\text{pre-train}} := p_t^{b, \text{pre-train}} - \hat{p}_t^b$$

- ▶ Loss function

$$\ell_\rho(\mathbf{x}_t) := \underbrace{\mathbf{1} \times \left( \sum_{h=1}^{H-1} (\epsilon_t^{k,h})^2 \right)}_{\text{opt. cond. cap.}} + \underbrace{\mathbf{0} \times \left( \sum_{h=1}^{H-1} (\epsilon_t^{b,h})^2 \right)}_{\substack{\text{opt. cond. bond} \\ =0}} + \mathbf{1} \times \underbrace{\left( \epsilon_t^{\text{pre-train}} \right)^2}_{\substack{\text{price pre-train error} \\ \text{train supervised}}}$$



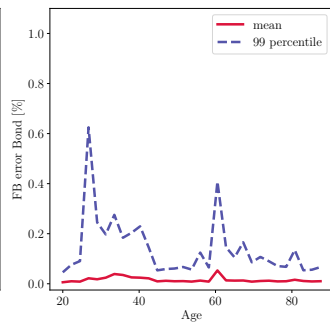
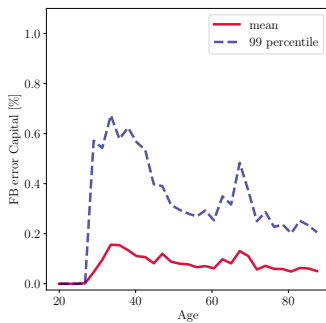
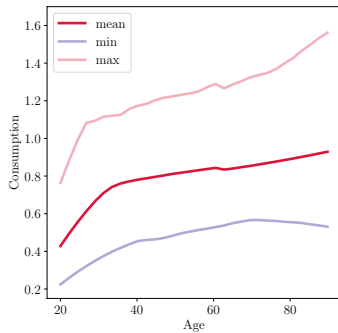
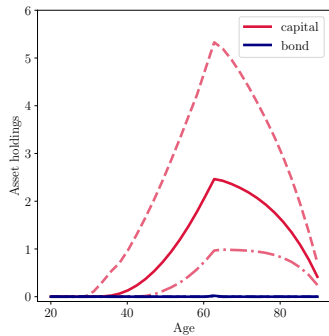
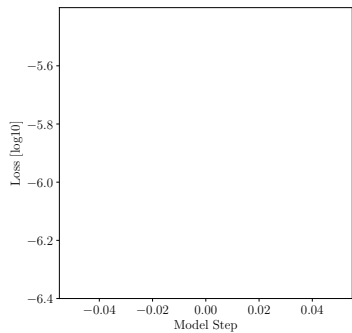
## Step 3: Slowly increase bond supply

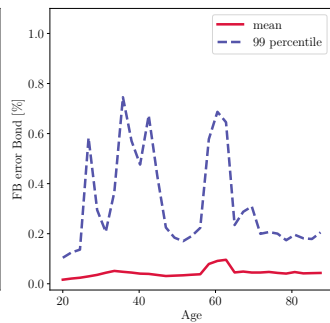
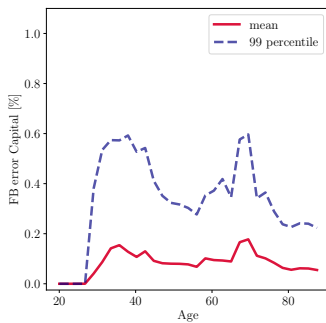
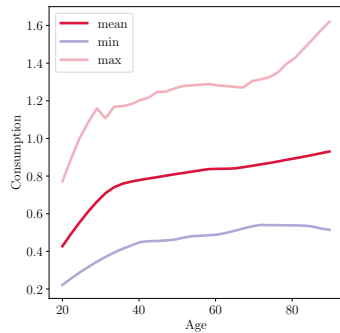
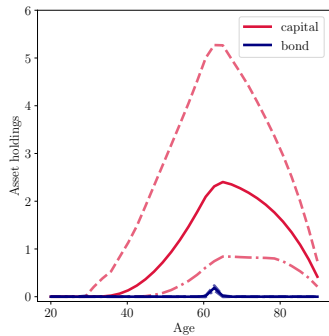
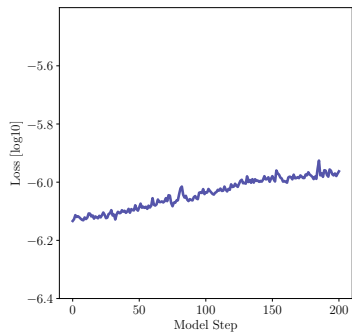
- ▶ Borrowing constraint  $\underline{b} = 0$ , increase net-supply from  $B = 0.1$  to  $B = 10$
- ▶ Neural network predicts

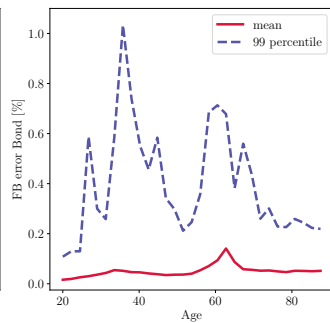
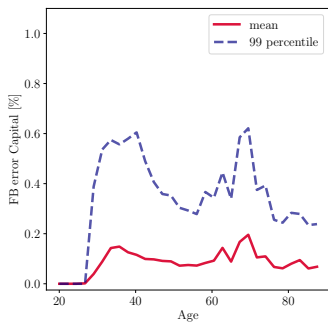
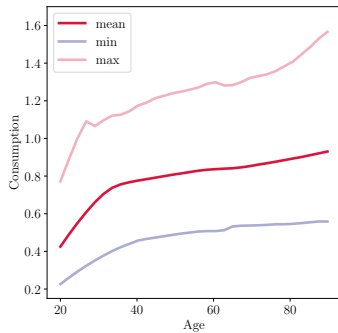
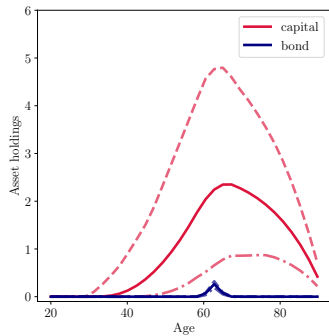
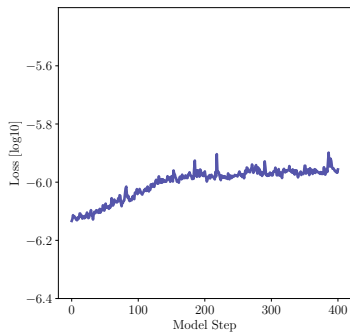
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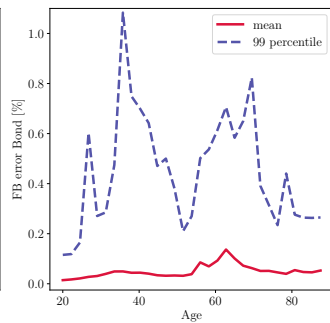
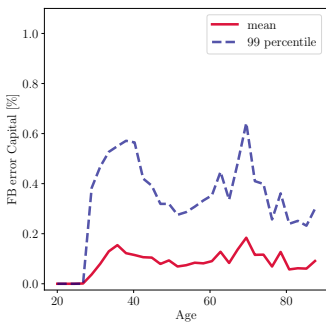
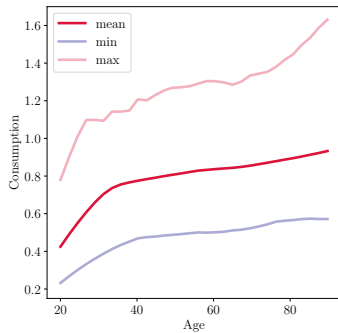
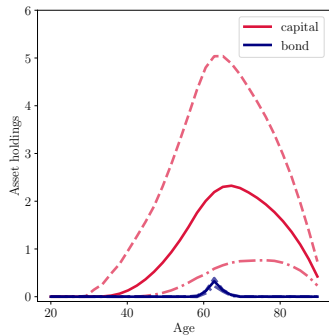
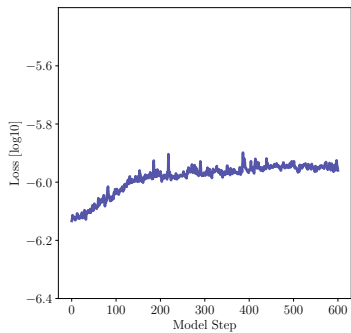
- ▶ Loss function

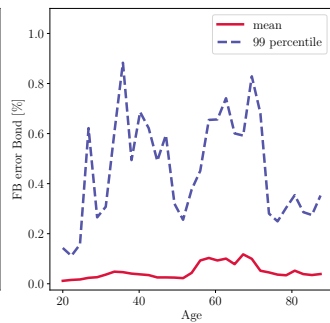
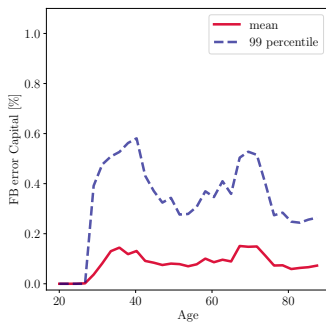
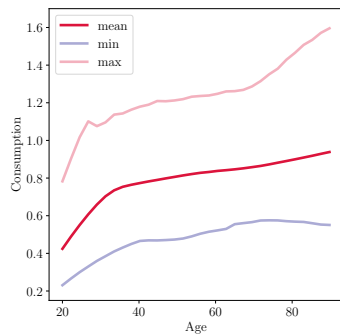
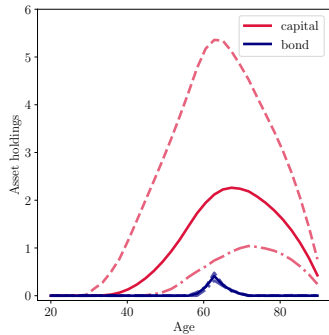
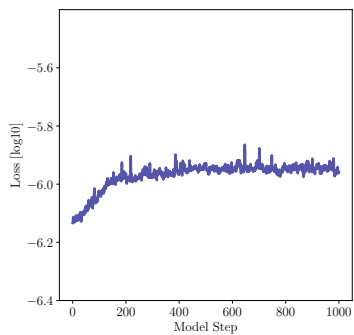
$$\ell_\rho(\mathbf{x}_t) := \underbrace{1 \times \left( \sum_{h=1}^{H-1} (\epsilon_t^{k,h})^2 \right)}_{\text{opt. cond. cap.}} + \underbrace{1 \times}_{\text{bond equ. cond. active}} \underbrace{\left( \sum_{h=1}^{H-1} (\epsilon_t^{b,h})^2 \right)}_{\text{opt. cond. bond}}$$



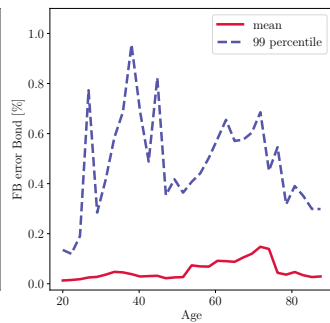
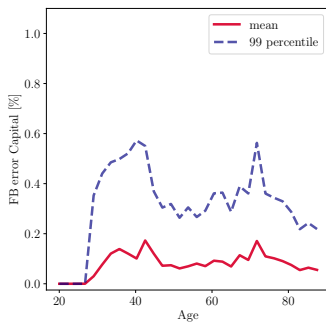
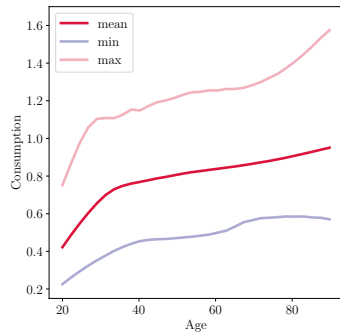
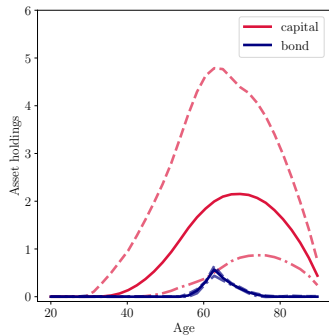
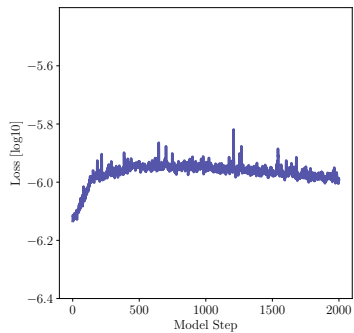


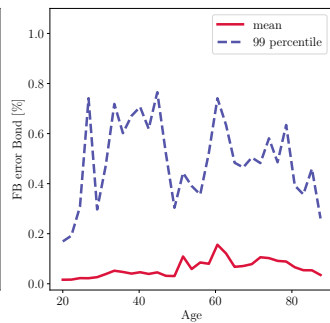
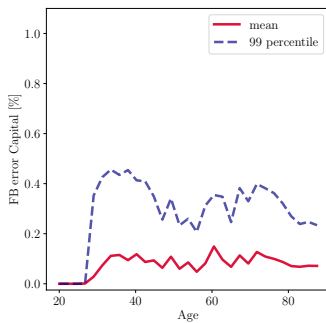
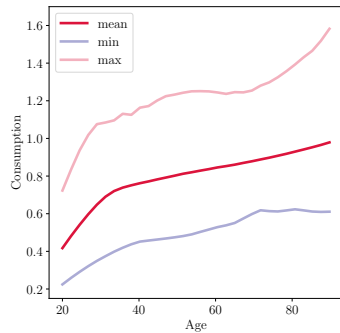
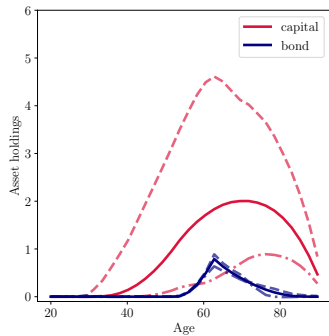
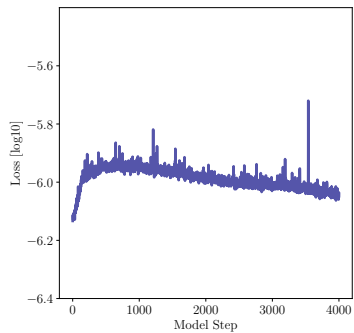


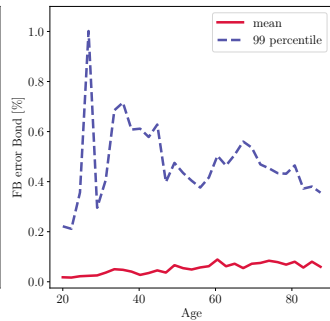
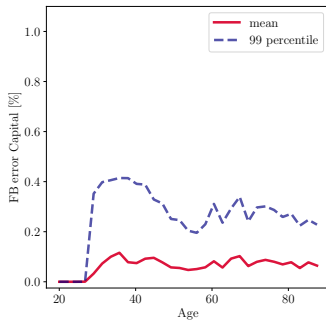
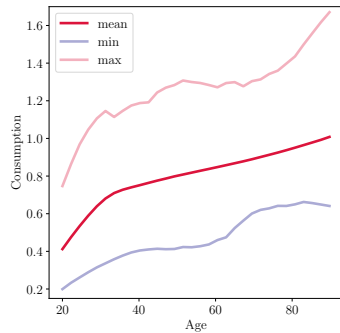
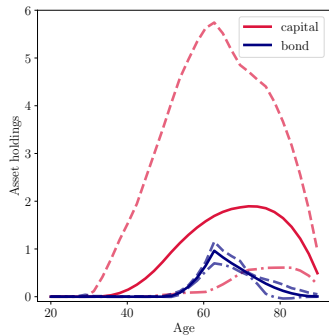
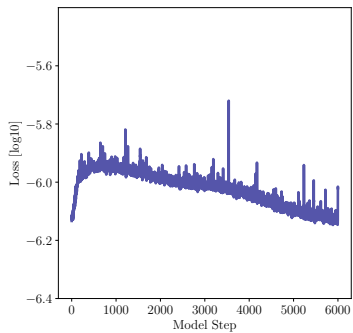


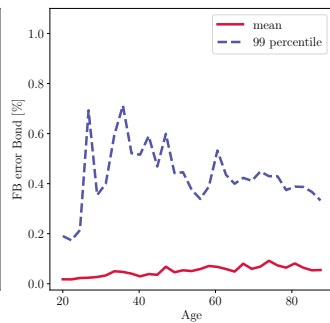
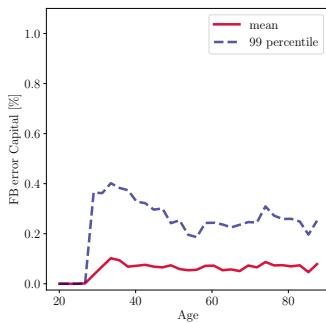
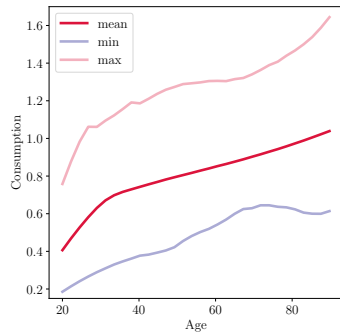
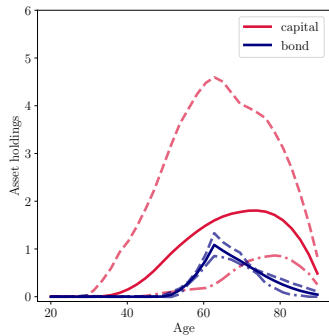
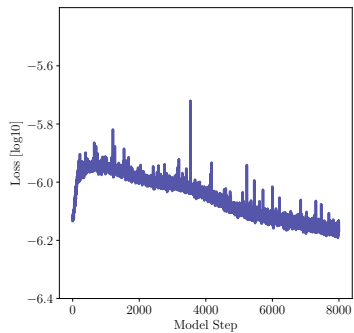


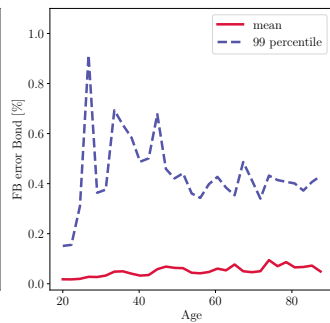
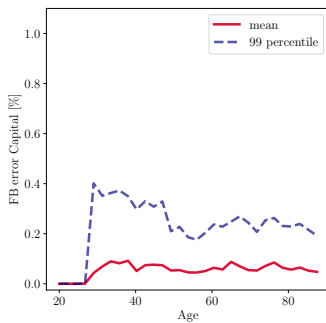
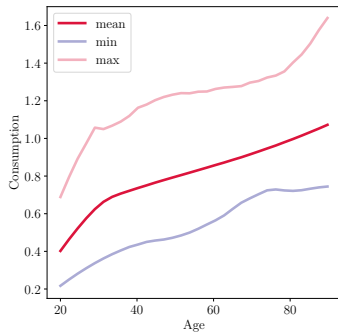
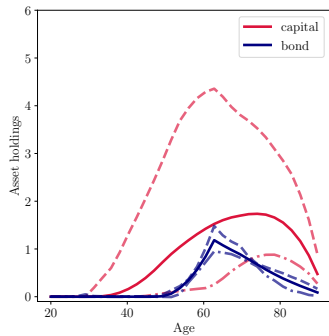
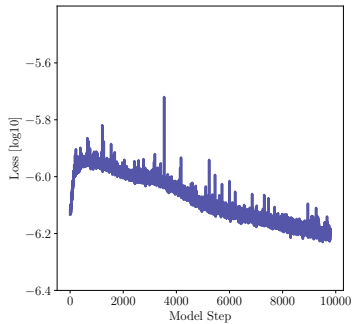












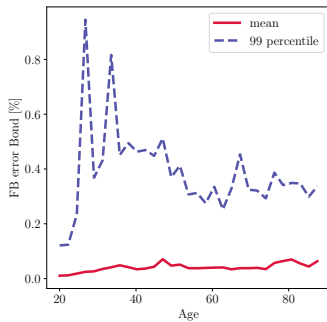
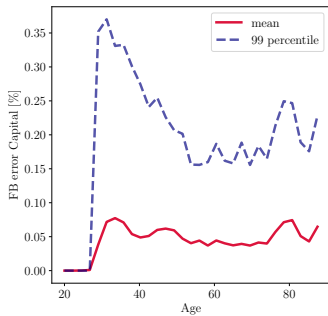
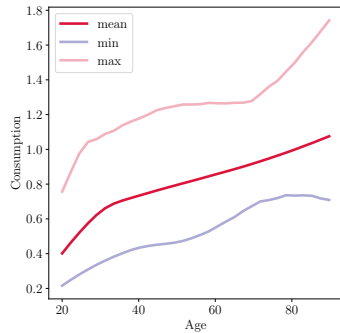
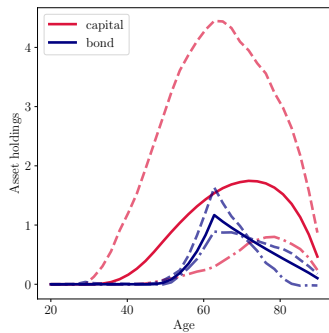
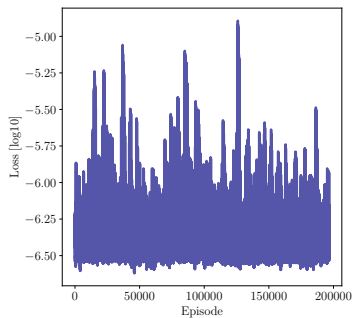
## Step 4: Training with the final supply

- ▶ Borrowing constraint  $\underline{b} = 0$ , bond at full net-supply from  $B = 10$
- ▶ Neural network predicts

$$\begin{aligned}\mathcal{N}_\rho^{\text{pre}}(\mathbf{x}_t) &= [\hat{k}_{t+1}^1, \dots, \hat{k}_{t+1}^{32}, \underbrace{0.01 \times \tilde{b}_{t+1}^1, \dots, 0.01 \times \tilde{b}_{t+1}^{32}}_{\text{bond policies active}}, \hat{p}_t^b] \\ \Rightarrow \mathcal{N}_\rho(\mathbf{x}_t) &= [\hat{k}_{t+1}^1, \dots, \hat{k}_{t+1}^{32}, \underbrace{\hat{b}_{t+1}^1, \dots, \hat{b}_{t+1}^{32}}_{\text{always add up the B}}, \hat{p}_t^b]\end{aligned}$$

- ▶ Loss function contains all remaining equilibrium conditions

$$\ell_\rho(\mathbf{x}_t) := \underbrace{1 \times \left( \sum_{h=1}^{H-1} (\epsilon_t^{k,h})^2 \right)}_{\text{opt. cond. cap.}} + \underbrace{1 \times \left( \sum_{h=1}^{H-1} (\epsilon_t^{b,h})^2 \right)}_{\text{opt. cond. bond}}$$



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- ▶ Key ideas in Azinovic et al. (2022):
  - ▶ **minimizing the error in the equilibrium conditions** allows training the neural network without labeled data  $\Rightarrow$  neural network can be trained on billions of states
  - ▶ training on the **simulated path**  $\Rightarrow$  focus training on where it matters
- ▶ Models with many assets remain challenging. To address this issue Azinovic and Žemlička (2023) introduce key innovations
  - ▶ **market clearing layers**, an economics-inspired neural network architecture
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- ▶ Also in the paper: quantitative life-cycle model with disaster risk, housing, equity and bonds in general equilibrium to study the intergenerational consequences of rare disasters (updated version coming soon)
- ▶ Other cool papers on deep learning based solution methods: Maliar et al. (2021); Kase et al. (2023); Gu et al. (2023); Kahou et al. (2021); Han et al. (2022); Valaitis and Villa (2024); Kahou et al. (2022); Fernández-Villaverde et al. (2023); Barnett et al. (2023); Jungerman (2023); Kahou et al. (2024)

Thank you!

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# Deep Neural Networks

# What is a deep neural net?

Consider:

$$\mathbf{input} := \mathbf{x} \rightarrow W_{\rho}^1 \mathbf{x} + \mathbf{b}_{\rho}^1 =: \mathbf{hidden\ 1}$$



# What is a deep neural net?

Consider:

$$\begin{aligned} \mathbf{input} &:= \mathbf{x} \rightarrow W_{\rho}^1 \mathbf{x} + \mathbf{b}_{\rho}^1 =: \mathbf{hidden\ 1} \\ &\rightarrow \mathbf{hidden\ 1} \rightarrow W_{\rho}^2(\mathbf{hidden\ 1}) + \mathbf{b}_{\rho}^2 =: \mathbf{hidden\ 2} \end{aligned}$$

# What is a deep neural net?

Consider:

$$\begin{aligned} \text{input} &:= \mathbf{x} \rightarrow W_{\rho}^1 \mathbf{x} + \mathbf{b}_{\rho}^1 =: \text{hidden 1} \\ \rightarrow \text{hidden 1} &\rightarrow W_{\rho}^2(\text{hidden 1}) + \mathbf{b}_{\rho}^2 =: \text{hidden 2} \\ \rightarrow \text{hidden 2} &\rightarrow W_{\rho}^3(\text{hidden 2}) + \mathbf{b}_{\rho}^3 =: \text{output} \end{aligned}$$

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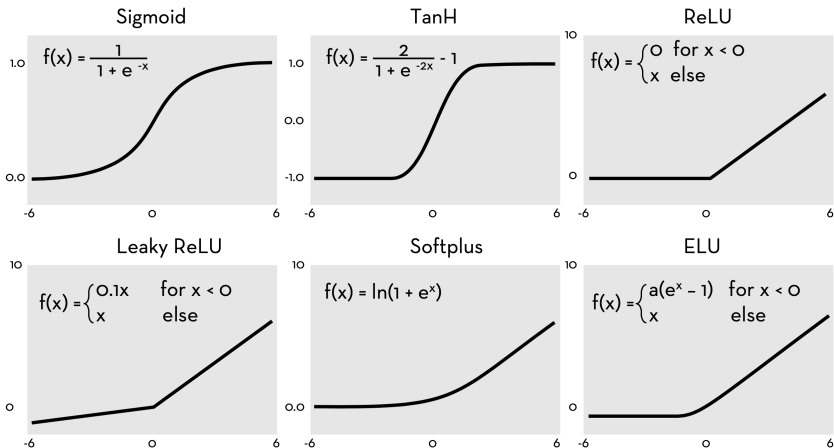
The parameters  $\rho$  of this procedure are the entries of the matrices  $(W_{\rho}^1, W_{\rho}^2, W_{\rho}^3)$  and vectors  $(\mathbf{b}_{\rho}^1, \mathbf{b}_{\rho}^2, \mathbf{b}_{\rho}^3)$ .

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Next ingredient: activation functions  $\phi^1, \phi^2, \phi^3$ . Activation functions could be any function, but popular are:



# What is a deep neural net? (cont.)

Now we get:

$$\begin{aligned} \text{input} &:= \mathbf{x} \rightarrow \phi^1(W_\rho^1 \mathbf{x} + \mathbf{b}_\rho^1) =: \text{hidden 1} \\ &\rightarrow \text{hidden 1} \rightarrow \phi^2(W_\rho^2(\text{hidden 1}) + \mathbf{b}_\rho^2) =: \text{hidden 2} \\ &\rightarrow \text{hidden 2} \rightarrow \phi^3(W_\rho^3(\text{hidden 2}) + \mathbf{b}_\rho^3) =: \text{output} \end{aligned}$$

The neural net is then given by the choice of activation functions and the parameters  $\rho$ .

▶ back

# Why neural networks?

Approximation method	High-dimensional input	Can resolve local features accurately	Irregularly shaped domain	Large amount of data
Polynomials	✓	✗	✓	✓
Splines	✗	✓	✗	✓
Adaptive (sparse) grids	✓	✓	✗	✓
Gaussian processes	✓	✓	✓	✗
Deep neural networks	✓	✓	✓	✓

**Table:** Taken from Azinovic et al. (2022).

# Innovation 1: Details on the market clearing transformation function

- ▶ Simple market clearing layer: subtract excess demand  $ED_t$  from initial predictions

$$ED_t := \sum_{h \in \mathcal{H}} \tilde{b}_{t+1}^h - B$$

$$\hat{b}_{t+1}^h := \tilde{b}_{t+1}^h - \frac{1}{H} ED_t$$

- ▶ Why this adjustment?

→ we try to minimize the modification to the initial predictions  $\{\tilde{b}_{t+1}^h\}_{h \in \mathcal{H}}$ .

- ▶ Final predictions  $\{\hat{b}_{t+1}^h\}_{h \in \mathcal{H}}$  solve

$$\arg \min_{\{x_{t+1}^h\}_{h \in \mathcal{H}}} \sum_{h \in \mathcal{H}} (x_{t+1}^h - \tilde{b}_{t+1}^h)^2$$

subject to

$$\sum_{h \in \mathcal{H}} x_{t+1}^h = B$$



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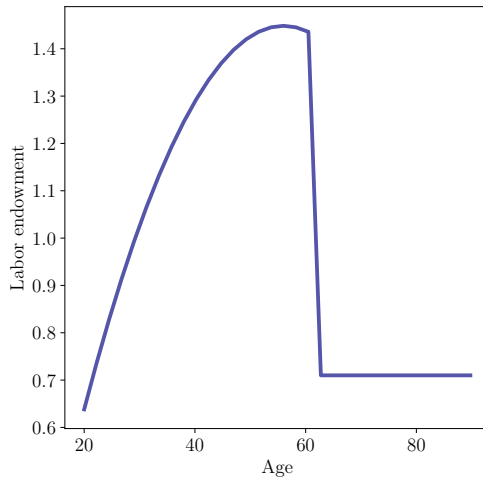
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- ▶ In the paper: enforcing market clearing & borrowing constraints using **implicit layer**

# Parameters

Parameters	$H$	$\beta$	$\gamma$	$\psi$	$\rho$	$\sigma$	$\alpha$
Values	32	0.912	4	0.1	0.693	0.052	0.333
Meaning	num. age groups	patience	RRA	adj. costs	pers. tfp	std. innov. tfp	cap. share



# Households' optimality conditions

$$\left. \begin{array}{l}
 1 = \frac{\beta E \left[ u'(c_{t+1}^{h+1}) (1 - \delta_{t+1} + r_{t+1} + 2\psi^k \Delta_{k,t+1}^{h+1}) + \mu_t^h \right]}{(1 + 2\psi^k \Delta_{k,t}^h) u'(c_t^h)} \\
 k_t^h \geq 0 \\
 \mu_t^h \geq 0 \\
 k_t^h \mu_t^h = 0
 \end{array} \right\} \Leftrightarrow \epsilon_t^{k,h} := \psi^{FB} \left( \frac{u'^{-1} \left( \beta E \left[ u'(c_{t+1}^{h+1}) \frac{(1 - \delta_{t+1} + r_{t+1} + 2\psi^k \Delta_{k,t+1}^{h+1})}{(1 + 2\psi^k \Delta_{k,t}^h)} \right] \right)}{c_t^h} - 1, \frac{k_t^h}{c_t^h} \right)$$

$$\left. \begin{array}{l}
 1 = \frac{\beta E \left[ u'(c_{t+1}^{h+1}) \right] + \lambda_t^h}{p_t^b u'(c_t^h)} \\
 b_t^h - \underline{b} \geq 0 \\
 \lambda_t^h \geq 0 \\
 (b_t^h - \underline{b}) \lambda_t^h = 0
 \end{array} \right\} \Leftrightarrow \epsilon_t^{b,h} := \psi^{FB} \left( \frac{u'^{-1} \left( \beta E \left[ \frac{1}{p_t^b} u'(c_{t+1}^{h+1}) \right] \right)}{c_t^h} - 1, \frac{b_t^h - \underline{b}}{c_t^h} \right)$$

where

$$\psi^{FB}(a, b) := a + b - \sqrt{a^2 + b^2}$$

► back